



# Fast Anisotropic Metasurface Analysis in FDTD using Surface Susceptibility Model

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# Abstract

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The FDTD methods combined with Surface Susceptibility Model (FDTD-SSM), compared to traditional brute force metasurface simulation, have been proved efficient and accurate for fast metasurface analysis. However, the present work is limited to scattering elements that are either isotropic or that have diagonal surface susceptibilities. This paper proposes a necessary extensions of Finite Difference Time Domain equations to analyze general anisotropic metasurfaces which have off-diagonal surface susceptibility tensors. At last, the Surface Susceptibility Model simulation results are validated by geometrical structure simulation results.

**Keyword:** Metasurfaces, GSTCs, FDTD, surface susceptibilities



# Biography

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Xiao Jia received the B.S. degree from Northwestern Polytechnical University, Xi'an, China, the M.S. degree from University of Chinese Academy of Sciences, Beijing, China, in 2013 and 2016, respectively, She received the Ph.D. degree from Tsinghua University, Beijing, China, in 2020, under the supervision of Prof. Fan Yang. From 2018 to 2019, she was a visiting student at Polytechnique Montréal, Montréal, Québec, Canada, with the supervision of Prof. Christophe Caloz.

She is currently a lecturer at Beijing Jiaotong University, Beijing, China. Her current research interests include computational electromagnetics, metasurfaces, computational electromagnetic, reflectarray and transmitarray.



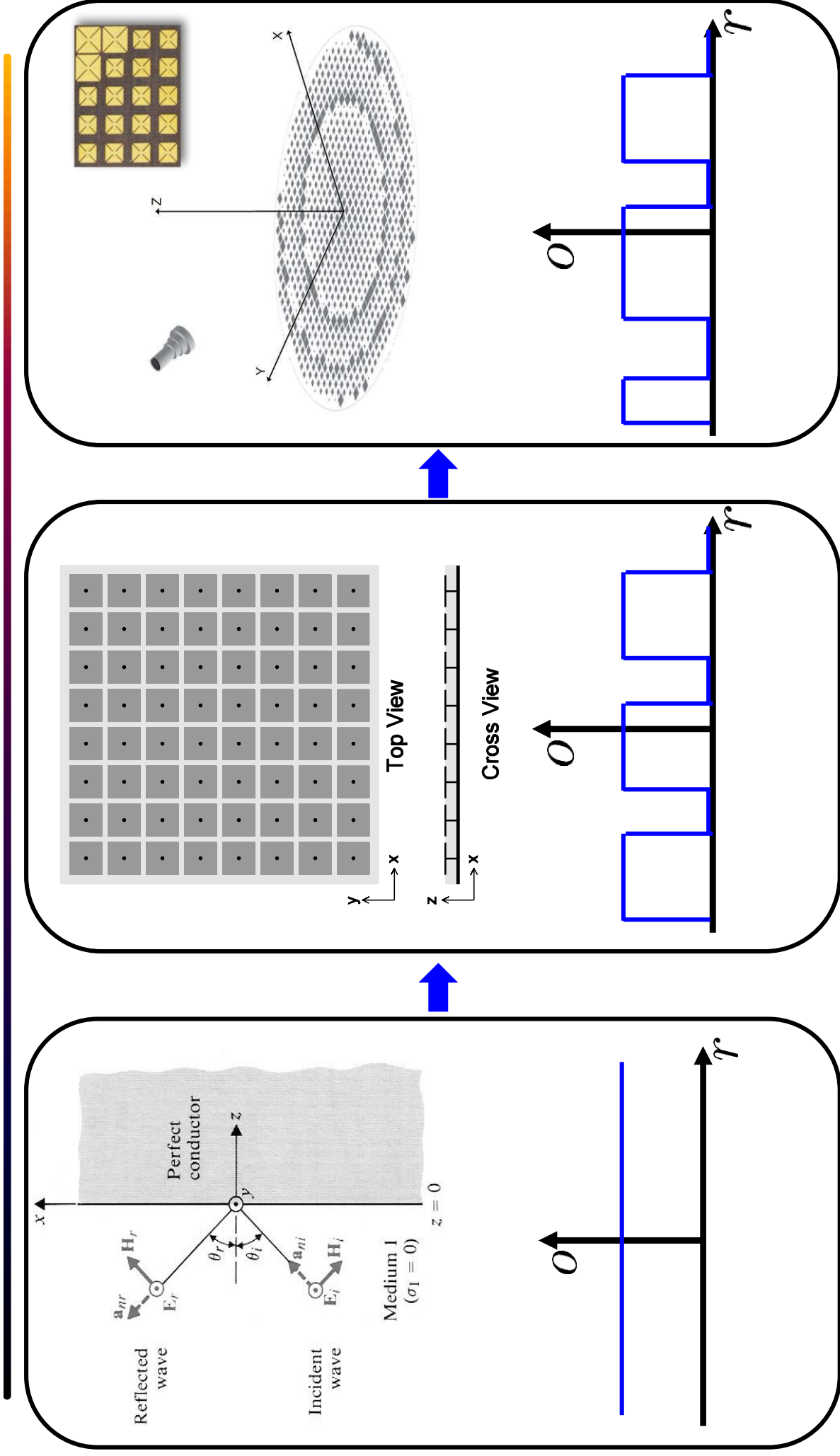
# Outline

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- ◆ **Introduction of Metasurfaces**
- ◆ **Modeling of metasurfaces**
- ◆ **FDTD-SSM Algorithm**
- ◆ **Numerical Experiments**
- ◆ **Conclusion**



# Development of Metasurfaces



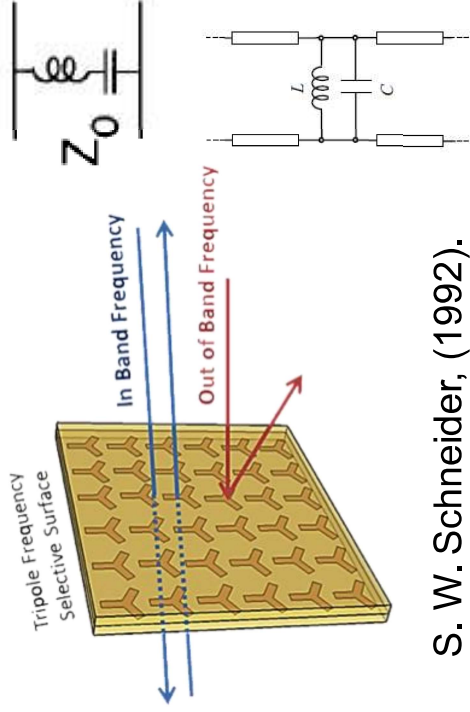
Ref: Yang F, Rahmat-Samii Y. Reflection phase characterizations of the EBG ground plane for low profile wire antenna applications[J]. IEEE Transactions on antennas and propagation, 2003, 51(10): 2691-2703.

Ref: Nayeri P, Yang F, Elsherbeni A Z. Reflectarray antennas: theory, designs, and applications[M]. John Wiley & Sons, 2018.



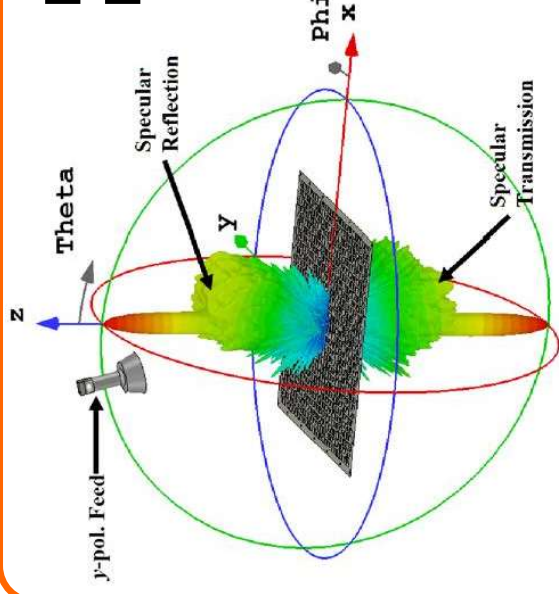
# Applications of Metasurfaces

## Frequency Selective Surfaces (FSSs)



S. W. Schneider, (1992).

## High-Gain Transmit-Reflect-Array

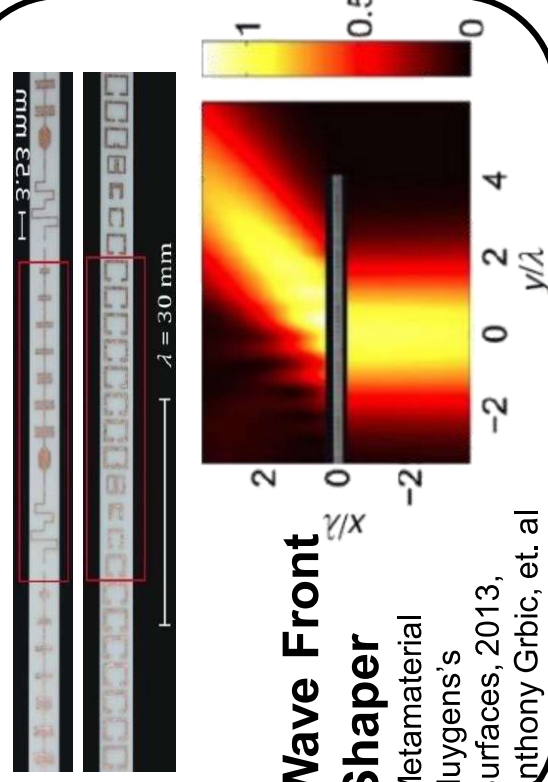


Fan Yang et al (2018).



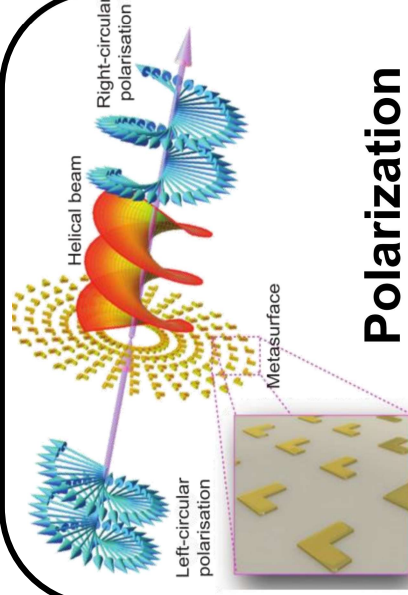
## Wave Front Shaper

Metamaterial Huygens's Surfaces, 2013, Anthony Grbic, et. al



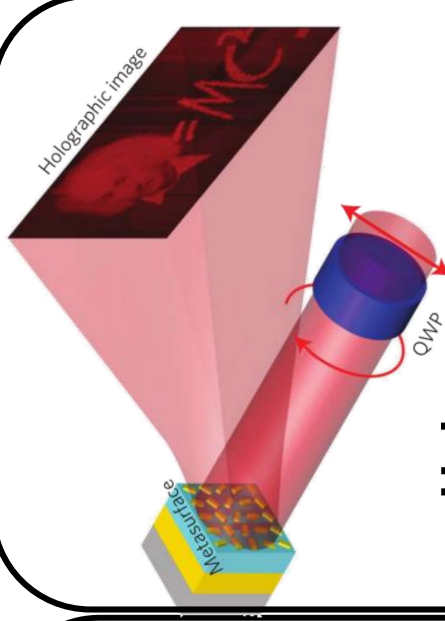
## Polarization Controller

C. Pfeiffer et al., PRA, (2014).



## Hologram

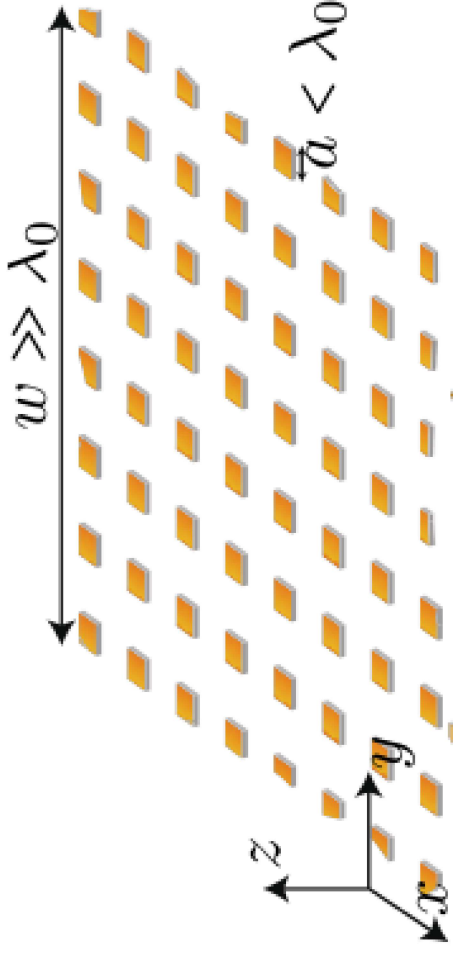
G. Zheng et al., Nat. Nano, (2015)



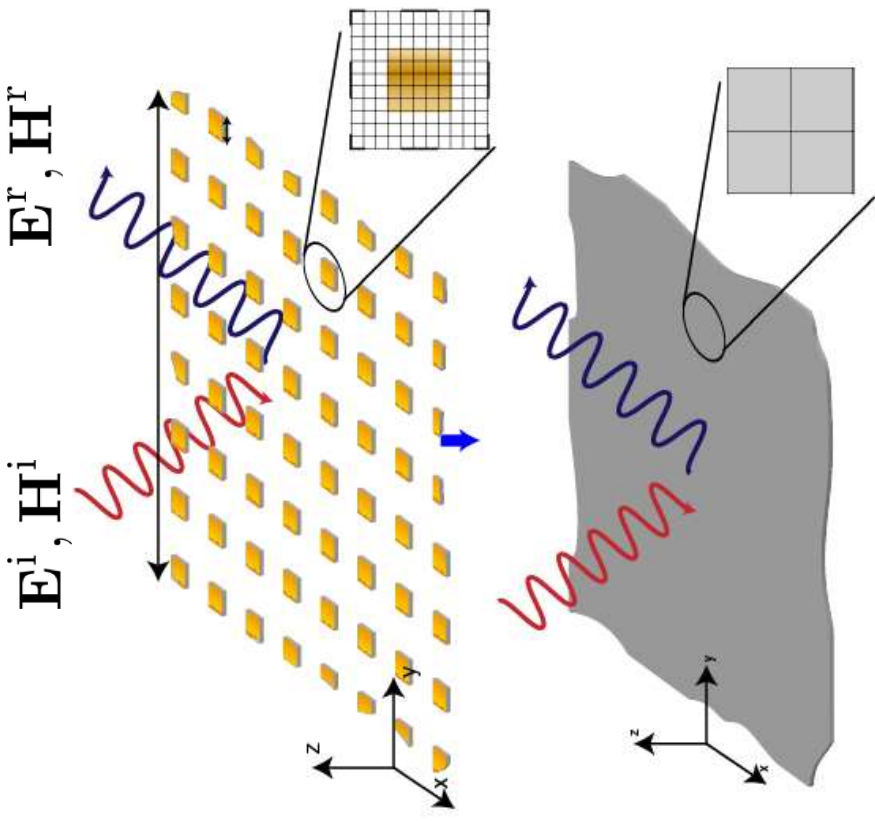


# Computational Challenges and Our Solutions

Electrically large global size



Subwavelength elements



## Remarks:

- Extremely dense meshes and huge number of unknowns leads to enormous computational problems, using brute force simulations.
- We propose to replace physical scattering-particle unit cells of metasurfaces by their corresponding homogenized surface model.





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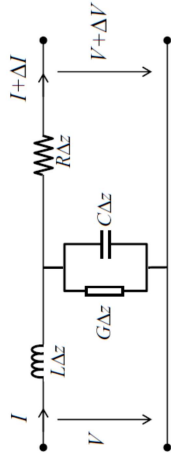


# System level models: from 1D to 3D

Engineers are constantly challenged with the temptation to search for optimum solutions for *complex engineering system designs*. Establishing *system level models* is a popular and efficient way.

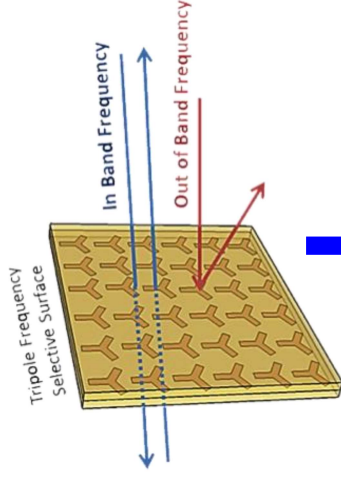
1D

Transmission Line



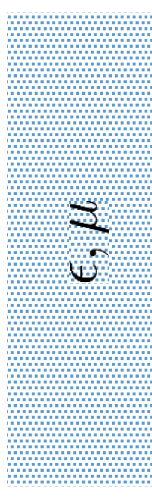
2D

Metasurface



3D

Metamaterial

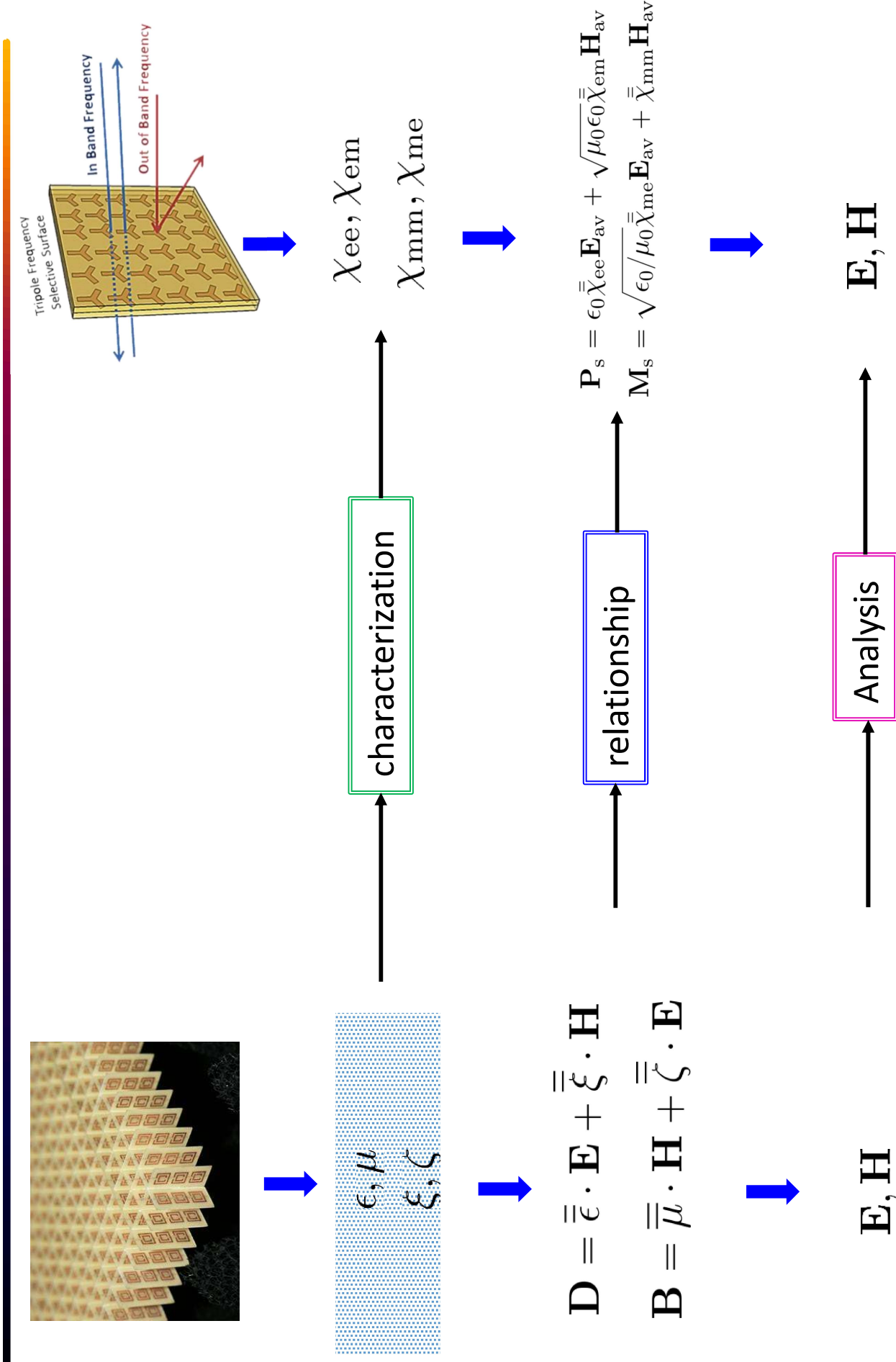


Remarks:

- The input and output of 1D case is **scalar variable**  $V(t), I(t)$ , while ours is **vectors**  $\vec{E}(\vec{r}, t), \vec{H}(\vec{r}, t)$ .
- Apart from magnitude, phase and frequency, we additionally considered polarization and propagation direction.



# From 3D Metamaterial to 2D Metasurface





# 2D Form of Surface Susceptibility Tensor

$$\begin{array}{c} \hat{z} \uparrow \\ \text{---} \quad \text{---} \quad \text{---} \\ \psi^+ \quad \text{---} \quad \text{---} \quad \text{---} \quad \text{---} \quad \text{---} \\ \psi^- \quad \text{---} \quad \text{---} \quad \text{---} \quad \text{---} \quad \text{---} \\ \text{---} \quad \text{---} \quad \text{---} \quad \text{---} \quad \text{---} \quad \text{---} \end{array} \quad \underline{\underline{\mathbf{P}_s, \mathbf{M}_s}}$$

$$\underline{\underline{\mathbf{P}_s}} = \epsilon_0 \bar{\chi}_{ee} \mathbf{E}_{av} + \sqrt{\mu_0 \epsilon_0} \bar{\chi}_{em} \mathbf{H}_{av}$$

$$\underline{\underline{\mathbf{M}_s}} = \sqrt{\epsilon_0 / \mu_0} \bar{\chi}_{me} \mathbf{E}_{av} + \bar{\chi}_{mm} \mathbf{H}_{av}$$

$$\Psi_{av} = \frac{\Psi^+ + \Psi^-}{2}, \quad \Psi = \mathbf{E}, \mathbf{H},$$

- Assumption 1: infinitely thin metamaterial:  $\rightarrow P_z = 0, M_x = 0, M_y = 0$
- Assumption 2: reciprocity  $\rightarrow \bar{\chi}_{ee}^T = \bar{\chi}_{ee}, \bar{\chi}_{mm}^T = \bar{\chi}_{mm}, \bar{\chi}_{me}^T = -\bar{\chi}_{em}$
- Assumption 3: magnetoelectric terms are zero:  $\rightarrow \bar{\chi}_{me} = 0, \bar{\chi}_{em} = 0$

$$\bar{\chi}_{ee} = \begin{bmatrix} \chi_{ee}^{xx} & \chi_{ee}^{xy} & \chi_{ee}^{xz} \\ \chi_{ee}^{yx} & \chi_{ee}^{yy} & \chi_{ee}^{yz} \\ \chi_{ee}^{zx} & \chi_{ee}^{zy} & \chi_{ee}^{zz} \end{bmatrix}$$

$$\bar{\chi}_{em} = \begin{bmatrix} \chi_{em}^{yx} & \chi_{em}^{xy} & \chi_{em}^{xz} \\ \chi_{em}^{yx} & \chi_{em}^{yy} & \chi_{em}^{yz} \\ \chi_{em}^{zx} & \chi_{em}^{zy} & \chi_{em}^{zz} \end{bmatrix}$$

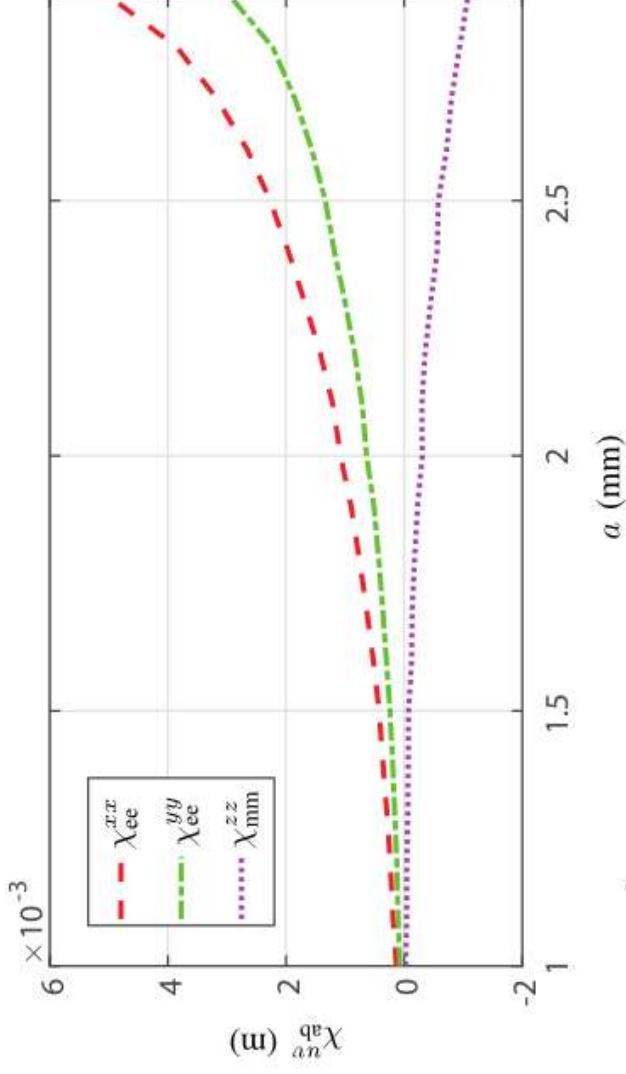
➔

$$\bar{\chi}_{ee} = \begin{bmatrix} \chi_{ee}^{xx} & \chi_{ee}^{xy} & 0 \\ \chi_{ee}^{yx} & \chi_{ee}^{yy} & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\bar{\chi}_{mm} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & \chi_{mm}^{zz} \end{bmatrix}$$



# Anisotropic SSM extraction



$$\bar{\bar{\chi}}_{ee} = \begin{bmatrix} \chi_{ee}^{xx} & \chi_{ee}^{xy} & 0 \\ \chi_{ee}^{yx} & \chi_{ee}^{yy} & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \bar{\bar{\chi}}_{mm} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & \chi_{mm}^{zz} \end{bmatrix}$$

$$\text{TE } \theta = 0 \quad \text{TM } \theta = 0$$

$$\chi_{ee}^{xx} = \frac{2(T_c^{\text{TTE}} - T_c^{\text{TTE}} T_c^{\text{TM}} + T_X^{\text{TTE}} T_X^{\text{TM}})}{j\omega\epsilon_0\eta(T_c^{\text{TTE}} T_c^{\text{TM}} - T_X^{\text{TTE}} T_X^{\text{TM}})} \Big|_{\theta=0},$$

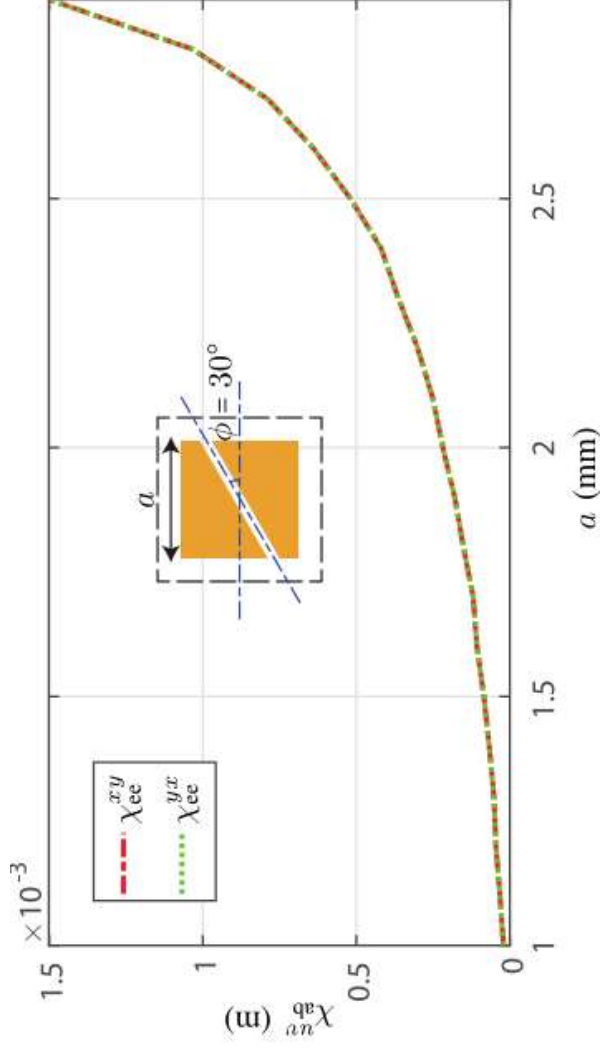
$$\chi_{ee}^{yy} = \frac{2(T_c^{\text{TM}} - T_c^{\text{TTE}} T_c^{\text{TM}} + T_X^{\text{TTE}} T_X^{\text{TM}})}{j\omega\epsilon_0\eta(T_c^{\text{TTE}} T_c^{\text{TM}} - T_X^{\text{TTE}} T_X^{\text{TM}})} \Big|_{\theta=0},$$

$$\chi_{ee}^{xy} = \frac{-2T_X^{\text{TTE}}}{j\omega\epsilon_0\eta(T_c^{\text{TTE}} T_c^{\text{TM}} - T_X^{\text{TTE}} T_X^{\text{TM}})} \Big|_{\theta=0},$$

$$\chi_{ee}^{yx} = \frac{-2T_X^{\text{TM}}}{j\omega\epsilon_0\eta(T_c^{\text{TTE}} T_c^{\text{TM}} - T_X^{\text{TTE}} T_X^{\text{TM}})} \Big|_{\theta=0}$$

$$\text{TE } \theta = \theta_0$$

$$\chi_{mm}^{zz} = \frac{(2 - 2T_c^{\text{TTE}}) \cos(\theta) - j\omega\epsilon_0\eta(\chi_{ee}^{yx} T_X^{\text{TTE}} \cos(\theta) + \chi_{ee}^{yy} T_c^{\text{TTE}})}{jk_x T_c^{\text{TTE}} \sin(\theta)} \Big|_{\theta=\theta_0}$$

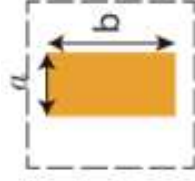




# Bi-axial Susceptibility Tensor

$$\bar{\bar{\chi}}_{ee} = \begin{bmatrix} \chi_{ee}^{xx} & \chi_{ee}^{xy} & 0 \\ \chi_{ee}^{yx} & \chi_{ee}^{yy} & 0 \\ 0 & 0 & 0 \end{bmatrix}$$
$$\bar{\bar{\chi}}_{mm} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & \chi_{mm}^{zz} \end{bmatrix}$$

Bi-axial



$$\bar{\bar{\chi}}_{ee} = \begin{bmatrix} \chi_{ee}^{xx} & 0 & 0 \\ 0 & \chi_{ee}^{yy} & 0 \\ 0 & 0 & 0 \end{bmatrix}$$
$$\bar{\bar{\chi}}_{mm} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & \chi_{mm}^{zz} \end{bmatrix}$$

## Remarks:

1. The unknowns are further reduced to 3 for bi-axial case.
2. Bi-axial case means that the structure do not generate cross polarization and transformation between electric to magnetic fields.



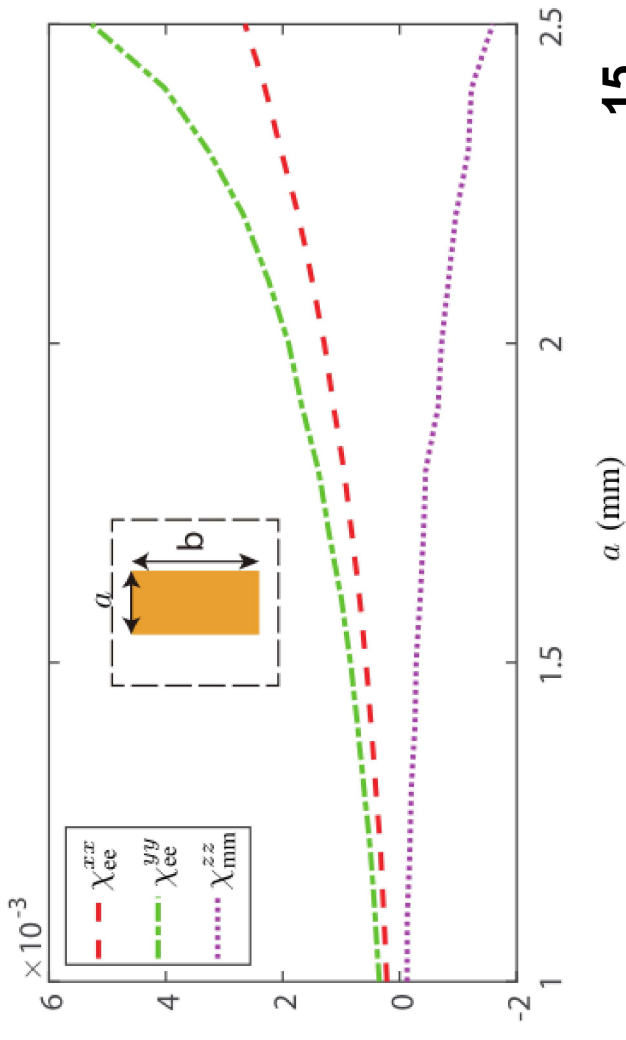
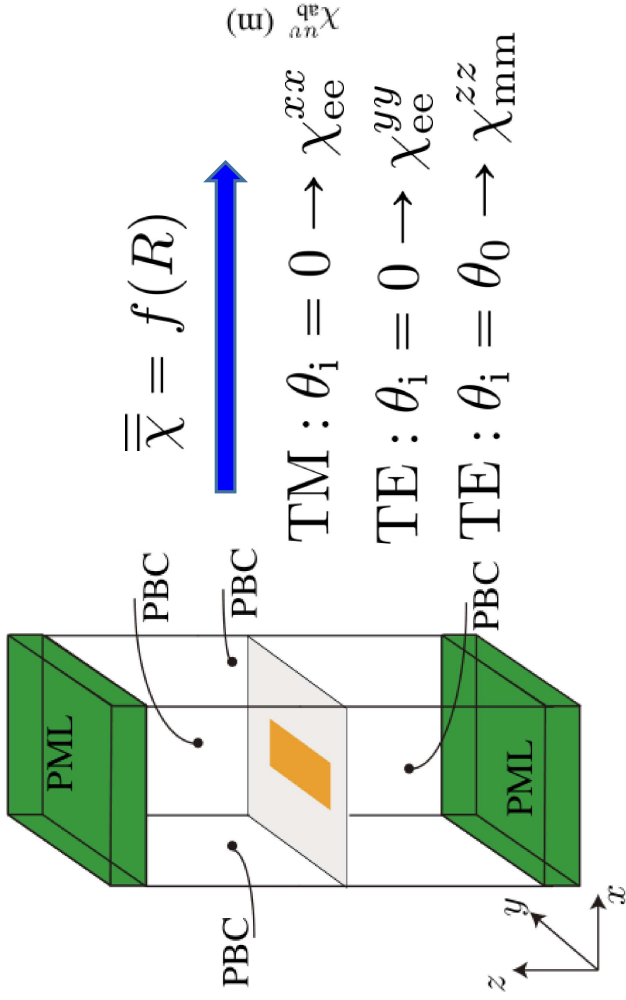
# Surface susceptibility for bi-axial case

The relationship between surface susceptibility and reflection coefficients:

$$TM_z : R_{TM}^\theta = \frac{j\omega\epsilon_0\chi_{ee}^{xx}\eta\cos\theta_i}{-2 - j\omega\epsilon_0\chi_{ee}^{xx}\eta\cos\theta_i}$$

$$TE_z : R_{TE}^\theta = \frac{j\omega\epsilon_0\chi_{ee}^{yy}\eta + jk_0\sin^2\theta_i\chi_{mm}^{zz}}{-2\cos\theta_i - j\omega\epsilon_0\chi_{ee}^{yy}\eta - jk_0\sin^2\theta_i\chi_{mm}^{zz}}$$

Three sets of simulation is required to extract the surface susceptibilities for bi-axial case:





# Outline

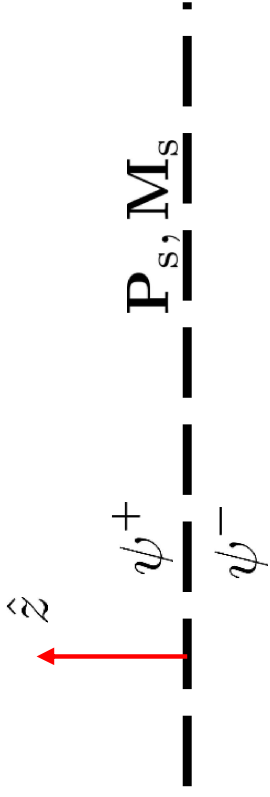
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# SSM & Surface Currents



$$\Psi_{av} = \frac{\Psi^+ + \Psi^-}{2}, \quad \Psi = \mathbf{E}, \mathbf{H},$$

$$\mathbf{P}_s = \epsilon_0 \bar{\chi}_{ee} \mathbf{E}_{av} + \sqrt{\mu_0 \epsilon_0} \bar{\chi}_{em} \mathbf{H}_{av}$$

$$\mathbf{M}_s = \sqrt{\epsilon_0 / \mu_0} \bar{\chi}_{me} \mathbf{E}_{av} + \bar{\chi}_{mm} \mathbf{H}_{av}$$

## Surface currents:

$$\mathbf{J}_{s,tot} = \mathbf{J}_{s,f} + \mathbf{J}_{s,p} + \mathbf{J}_{s,m}$$

$$= \mathbf{J}_{s,f} + \frac{\partial \mathbf{P}_{s,\parallel}}{\partial t} + (\nabla \times \mathbf{M}_s)_{\parallel} \quad (\text{A/m})$$

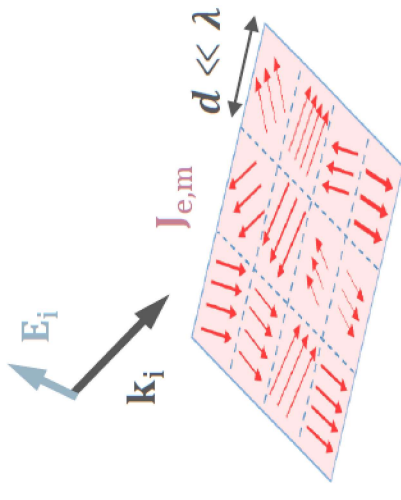
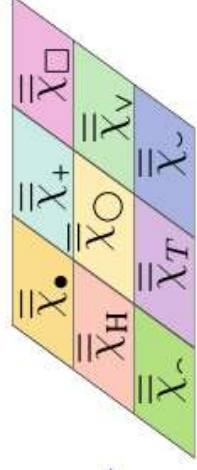
$$\mathbf{K}_{s,tot} = \mathbf{K}_{s,f} + \mathbf{K}_{s,m} + \mathbf{K}_{s,p}$$

$$= \mathbf{K}_{s,f} + \mu_0 \frac{\partial \mathbf{M}_{s,\parallel}}{\partial t} + [\nabla \times (\mathbf{P}_s / \epsilon_0)]_{\parallel} \quad (\text{V/m})$$

physical metasurface



$\bar{\chi}$ -modeled metasurface



Ref 1: Idemen, M. Mithat. Discontinuities in the electromagnetic field. Vol. 40. John Wiley & Sons, 2011.

Ref 2: Achouri, Karim, Mohamed A. Salem, and Christophe Caloz. "General metasurface synthesis based on susceptibility tensors." IEEE Transactions on Antennas and Propagation 63.7 (2015): 2977-2991.

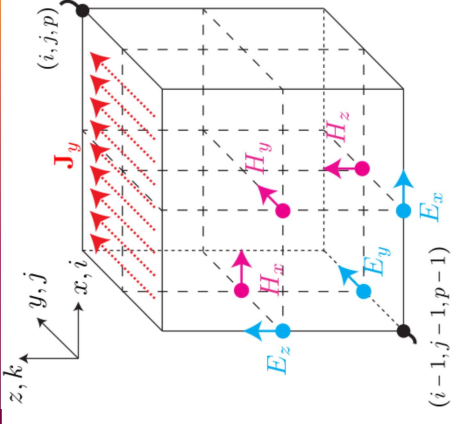
Ref 3: Kuester, Edward F., et al. "Averaged transition conditions for electromagnetic fields at a metamaterial." IEEE Transactions on Antennas and Propagation 51.10 (2003): 2641-2651.



# Surface currents in FDTD

$$\oint \mathbf{H} \cdot d\mathbf{l} = \epsilon_0 \iint \frac{\partial \mathbf{E}}{\partial t} \cdot d\mathbf{s} + \iint \mathbf{J}_s \cdot \delta(z) d\mathbf{s}$$

↓ Discretization in Yee cell



$$\begin{aligned} (H_x^{n-1/2}(i, j, p) - H_x^{n-1/2}(i, j, p-1))\Delta x + (H_z^{n-1/2}(i, j, p) - H_z^{n-1/2}(i-1, j, p))\Delta z \\ = \epsilon_0 \frac{E_y^n(i, j, p) - E_y^{n-1}(i, j, p)}{\Delta t} \Delta x \Delta z + J_y^{n-1/2}(i, j, p) \Delta x \end{aligned}$$

↓ Rearranging

$$\begin{aligned} E_y^n(i, j, p) &= E_y^{n-1}(i, j, p) + \frac{\Delta t}{\epsilon_0} \\ &\left[ \frac{H_x^{n-1/2}(i, j, p) - H_x^{n-1/2}(i, j, p-1)}{\Delta z} - \frac{H_z^{n-1/2}(i, j, p) - H_z^{n-1/2}(i-1, j, p)}{\Delta x} \right. \\ &\quad \left. - \frac{\Delta t J_y^{n-1/2}(i, j, p)}{\epsilon_0} \right]. \end{aligned}$$



# Bi-axial SSM in FDTD

$$\mathbf{P} = \epsilon_0 \begin{bmatrix} \chi_{ee}^{xx} & 0 & 0 \\ 0 & \chi_{ee}^{yy} & 0 \\ 0 & 0 & 0 \end{bmatrix} \mathbf{E}, \quad \mathbf{M} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & \chi_{mm}^{zz} \end{bmatrix} \mathbf{H}$$

$$\mathbf{J}_s = \frac{\partial \mathbf{P}}{\partial t} + \nabla \times \mathbf{M}$$

$$\uparrow \quad J_y = (\epsilon_0 \chi_{ee}^{yy} \frac{\partial E_y}{\partial t} - \frac{\partial(\chi_{mm}^{zz} H_z)}{\partial x}) \hat{y}$$

$$E_y^n(i, j, p) = E_y^{n-1}(i, j, p) + \frac{\Delta t}{\epsilon_0} \left[ \frac{H_x^{n-1/2}(i, j, p) - H_x^{n-1/2}(i, j, p-1)}{\Delta z} \quad H_z^{n-1/2}(i, j, p) - H_z^{n-1/2}(i-1, j, p) \right] \Delta x$$

$$- \frac{\Delta t}{\epsilon_0} \frac{J_y^{n-1/2}(i, j, p)}{\Delta z}$$

$$E_y^n(i, j, p) = E_y^{n-1}(i, j, p) + \frac{\Delta t \Delta z}{\epsilon_0(\Delta z + \tilde{\chi}_{ee}^{yy}(i, j, p))} \left[ \frac{H_x^{n-1/2}(i, j, p) - H_x^{n-1/2}(i, j, p-1)}{\Delta z} \quad H_z^{n-1/2}(i, j, p) - H_z^{n-1/2}(i-1, j, p) \right] +$$

$$\frac{\Delta t}{\epsilon_0(\Delta z + \tilde{\chi}_{ee}^{yy}(i, j, p))} \frac{\chi_{mm}^{zz}(i, j, p) H_z^{n-1/2}(i, j, p) - \chi_{mm}^{zz}(i-1, j, p) H_z^{n-1/2}(i-1, j, p)}{\Delta x}$$

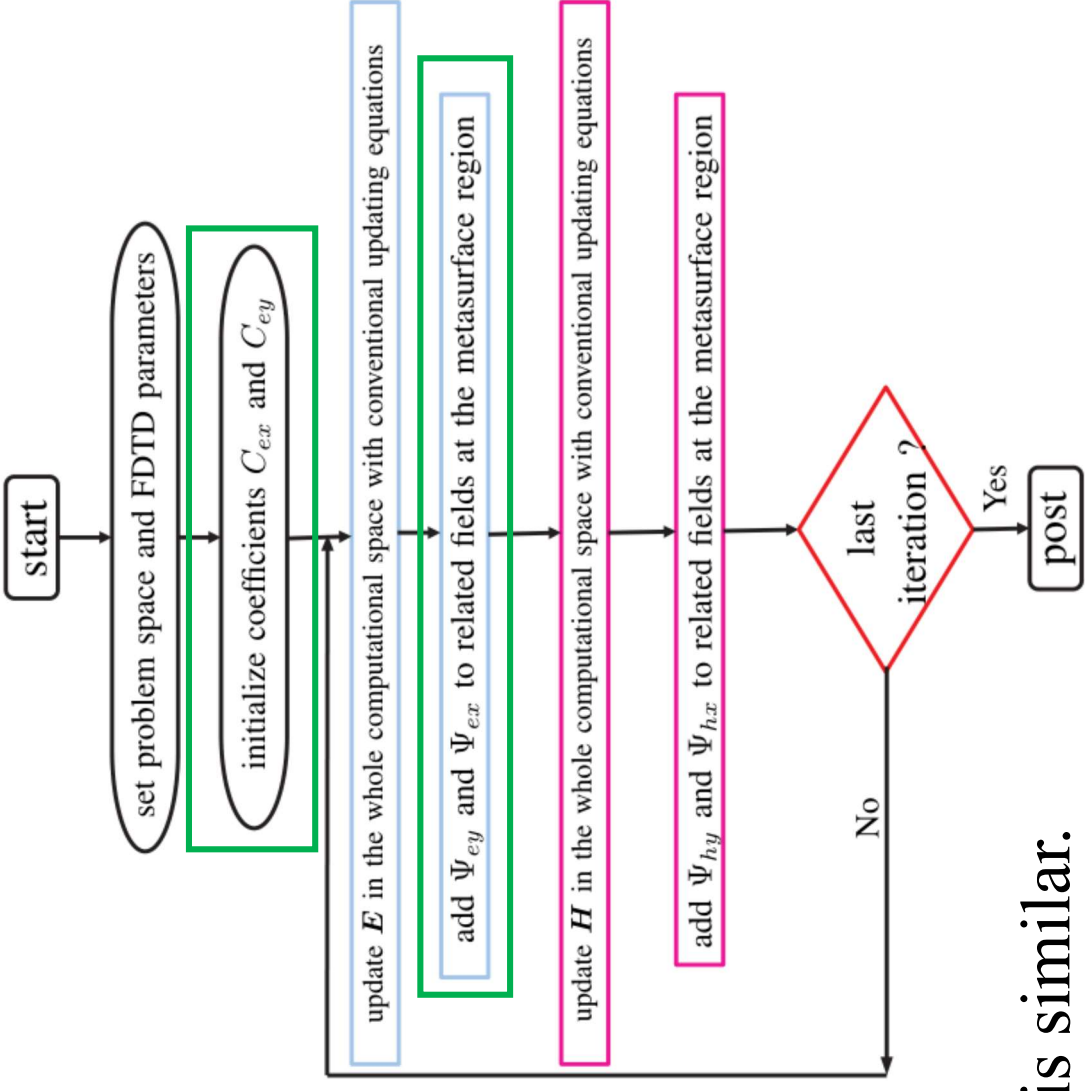


# Flowchart of FDTD-SSM

$$C_{ey} = \frac{\Delta t \Delta z}{\epsilon_0(\Delta z + \tilde{\chi}_{ee}^{yy}(i, j, p))}$$

$$\Psi_{ey} = \frac{\Delta t}{\epsilon_0(\Delta z + \tilde{\chi}_{ee}^{yy}(i, j, p))} \left[ \chi_{mm}^{zz}(i, j, p) H_z^{n-1/2}(i, j, p) - \chi_{mm}^{zz}(i-1, j, p) H_z^{n-1/2}(i-1, j, p) \right] \frac{\Delta x}{\Delta z}$$

$$E_y^n(i, j, p) = E_y^{n-1}(i, j, p) + C_{ey} \left[ \frac{H_x^{n-1/2}(i, j, p) - H_x^{n-1/2}(i, j, p-1)}{\Delta z} - \frac{H_z^{n-1/2}(i, j, p) - H_z^{n-1/2}(i-1, j, p)}{\Delta x} \right] + \Psi_{ey}$$



The updating procedure of  $E_x$  is similar.



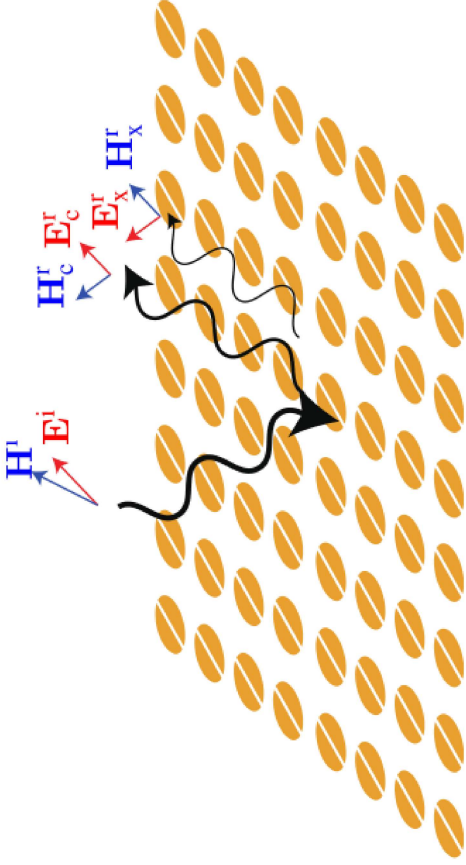
# Anisotropic FDTD-SSM

$$\bar{\bar{\chi}}_{ee} = \begin{bmatrix} \chi_{ee}^{xx} & \chi_{ee}^{xy} & 0 \\ \chi_{ee}^{yx} & \chi_{ee}^{yy} & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \bar{\bar{\chi}}_{mm} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & \chi_{mm}^{zz} \end{bmatrix}$$

$$\mathbf{J}_s = \frac{\partial \mathbf{P}}{\partial t} + \nabla \times \mathbf{M}$$

$$\mathbf{J}_y = (\epsilon_0 \chi_{ee}^{yy} \frac{\partial E_y}{\partial t} + \epsilon_0 \chi_{ee}^{yx} \frac{\partial E_x}{\partial t} - \frac{\partial (\chi_{mm}^{zz} H_z)}{\partial x}) \hat{y}$$

$$E_y^n(i, j, p) = E_y^{n-1}(i, j, p) + \frac{\Delta t}{\epsilon_0} \left[ \frac{H_x^{n-1/2}(i, j, p) - H_x^{n-1/2}(i, j, p-1)}{\Delta z} - \frac{H_z^{n-1/2}(i, j, p) - H_z^{n-1/2}(i-1, j, p)}{\Delta x} - \frac{\Delta t J_y(i, j, p)}{\epsilon_0 \Delta z} \right]$$



Because of the existence of the off-diagonal surface susceptibilities, the time differential equations of  $E_x$  and  $E_y$  are ***coupled*** for anisotropic case.

$$E_y^n(i, j, p) = E_y^{n-1}(i, j, p) + \frac{\Delta t}{\epsilon_0} \left[ \frac{H_x^{n-1/2}(i, j, p) - H_x^{n-1/2}(i, j, p-1)}{\Delta z} - \frac{H_z^{n-1/2}(i, j, p) - H_z^{n-1/2}(i-1, j, p)}{\Delta x} - \frac{\chi_{ee}^{yy} E_y^n(i, j, p) - E_y^{n-1}(i, j, p)}{\Delta t} - \frac{\chi_{ee}^{yx} E_x^n(i, j, p) - E_x^{n-1}(i, j, p)}{\Delta t} - \frac{\Delta t \chi_{mm}^{zz} H_z^{n-1/2}(i, j, p) - \chi_{mm}^{zz} H_z^{n-1/2}(i-1, j, p)}{\epsilon_0 \Delta z} \right]$$



# Matrix form of anisotropic SSM

$$\oint \mathbf{H} \cdot d\mathbf{l} = \epsilon_0 \iint \frac{\partial \mathbf{E}}{\partial t} \cdot d\mathbf{s} + \iint \mathbf{J}_s \cdot \delta(z) d\mathbf{s}$$

$$J_x = (\epsilon_0 \chi_{ee}^{xx} \frac{\partial E_x}{\partial t} + \epsilon_0 \chi_{ee}^{xy} \frac{\partial E_y}{\partial t} + \frac{\partial(\chi_{mm}^{zz} H_z)}{\partial x}) \hat{y} \quad \downarrow \quad J_y = (\epsilon_0 \chi_{ee}^{yy} \frac{\partial E_y}{\partial t} + \epsilon_0 \chi_{ee}^{yx} \frac{\partial E_x}{\partial t} - \frac{\partial(\chi_{mm}^{zz} H_z)}{\partial x}) \hat{y}$$

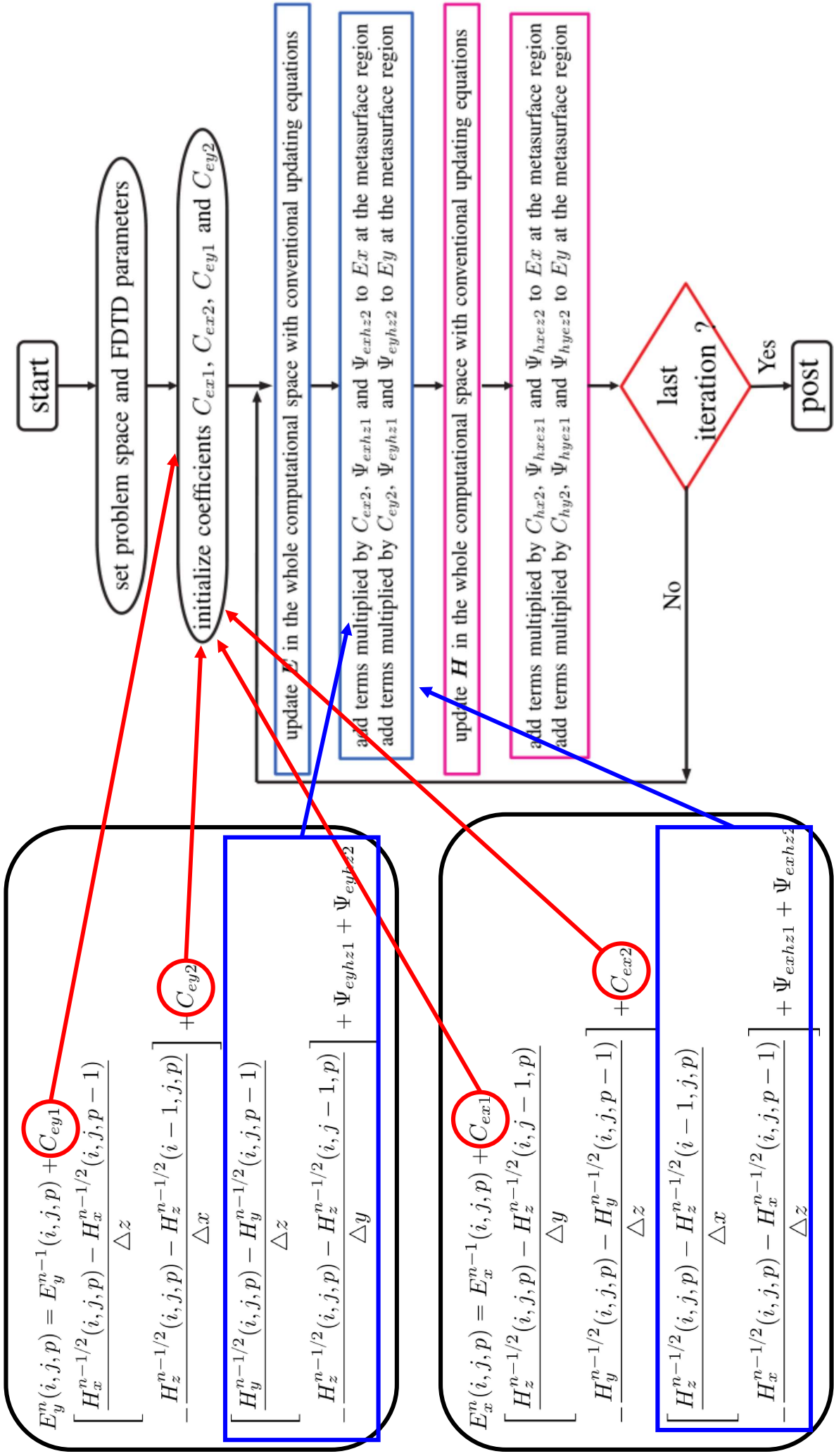
$$\begin{bmatrix} \frac{\partial H_z}{\partial y} - \frac{\partial H_y}{\partial z} \\ \frac{\partial H_x}{\partial z} - \frac{\partial H_z}{\partial x} \end{bmatrix} = \epsilon_0 \begin{bmatrix} 1 + \frac{\chi_{ee}^{xx}}{\Delta z} & \frac{\chi_{ee}^{xy}}{\Delta z} \\ \frac{\chi_{ee}^{yx}}{\Delta z} & 1 + \frac{\chi_{ee}^{yy}}{\Delta z} \end{bmatrix} \begin{bmatrix} \frac{\partial E_x}{\partial t} \\ \frac{\partial E_y}{\partial t} \end{bmatrix} + \frac{1}{\Delta z} \begin{bmatrix} \frac{\partial(\chi_{mm}^{zz} H_z)}{\partial y} \\ \frac{\partial(-\chi_{mm}^{zz} H_z)}{\partial x} \end{bmatrix}$$

**Matrix inversion**

$$\begin{bmatrix} \frac{\partial E_x}{\partial t} \\ \frac{\partial E_y}{\partial t} \end{bmatrix} = \epsilon_0 \begin{bmatrix} 1 + \frac{\chi_{ee}^{xx}}{\Delta z} & \frac{\chi_{ee}^{xy}}{\Delta z} \\ \frac{\chi_{ee}^{yx}}{\Delta z} & 1 + \frac{\chi_{ee}^{yy}}{\Delta z} \end{bmatrix}^{-1} \begin{bmatrix} \frac{\partial H_z}{\partial y} - \frac{\partial H_y}{\partial z} \\ \frac{\partial H_x}{\partial z} - \frac{\partial H_z}{\partial x} \end{bmatrix} + \frac{1}{\Delta z} \begin{bmatrix} 1 + \frac{\chi_{ee}^{xx}}{\Delta z} & \frac{\chi_{ee}^{xy}}{\Delta z} \\ \frac{\chi_{ee}^{yx}}{\Delta z} & 1 + \frac{\chi_{ee}^{yy}}{\Delta z} \end{bmatrix}^{-1} \begin{bmatrix} \frac{\partial(\chi_{mm}^{zz} H_z)}{\partial y} \\ \frac{\partial(-\chi_{mm}^{zz} H_z)}{\partial x} \end{bmatrix}$$



# Flowchart of anisotropic FDTD-SSM





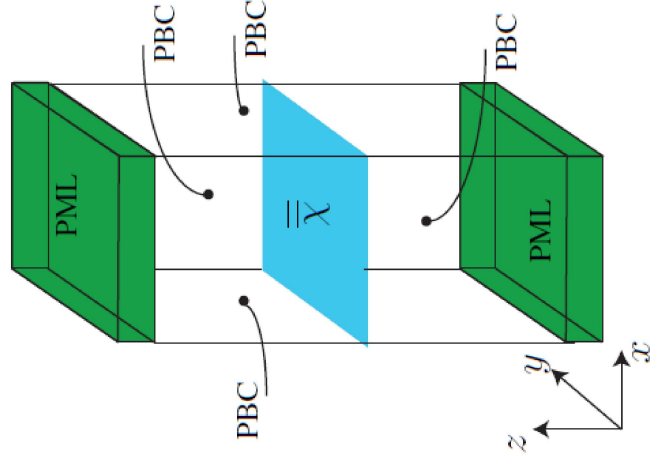
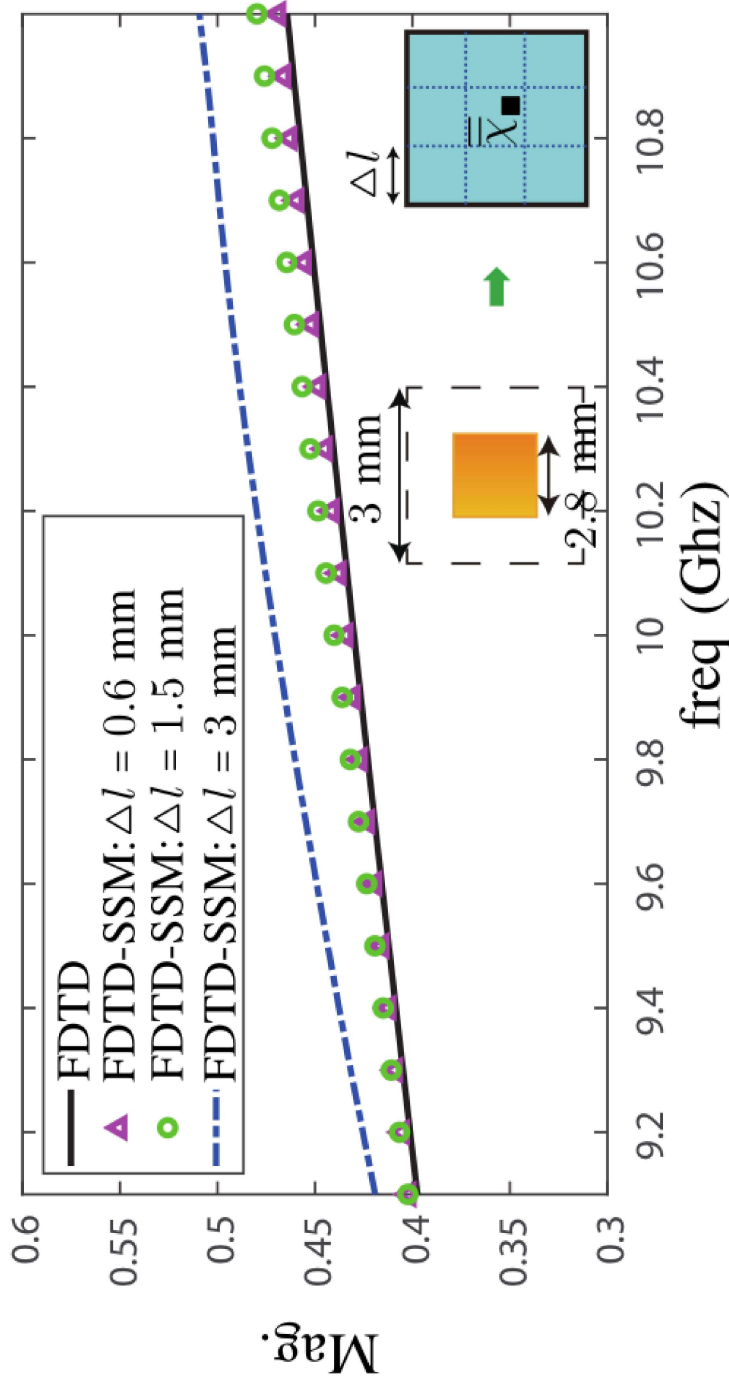
# Outline

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- ◆ **Introduction of Metasurfaces**
- ◆ **Modeling of metasurface**
- ◆ **FDTD-SSM Algorithm**
- ◆ **Numerical Experiments**
  - **Uniaxial element**
  - **Biaxial element**
  - **General anisotropic element**
- ◆ **Conclusion**



# Uniaxial FDTD-SSM



## Remarks:

1. The meshing lattice size of conventional FDTD is  $\frac{\lambda}{600} = 0.05$  mm.
2. As the meshing lattice size of FDTD-SSM decreasing to  $\frac{\lambda}{50} = 0.6$  mm =  $12 \times 0.05$  mm, its results overlap with that of conventional FDTD.



# Biaxial FDTD-SSM

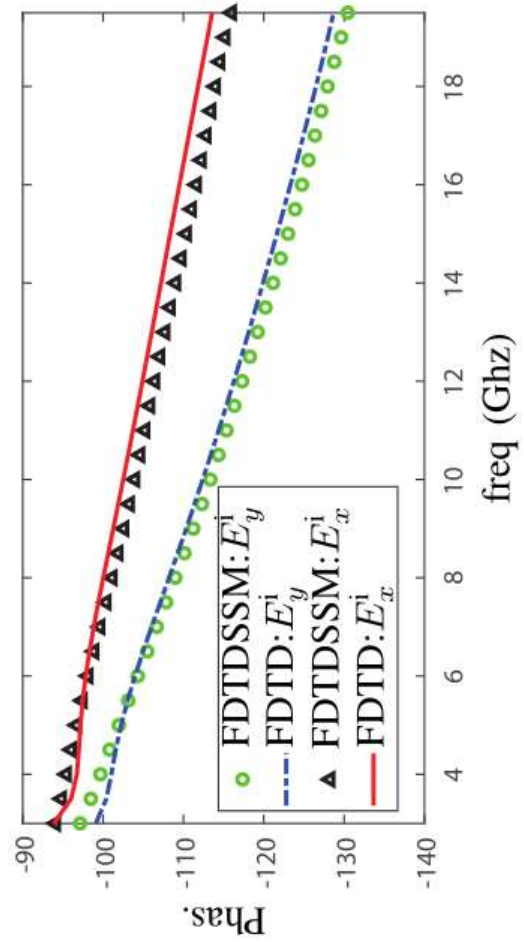
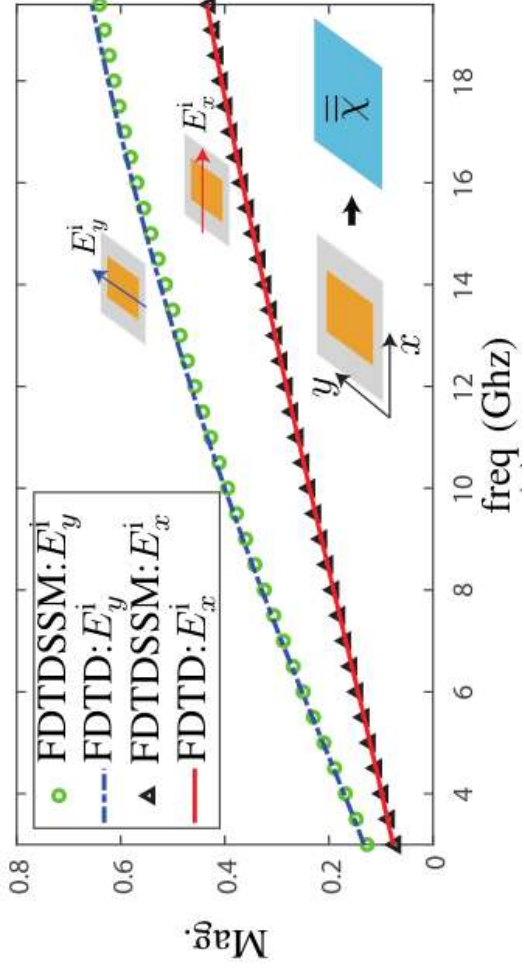


TABLE I  
COMPUTATIONAL RESOURCES CONSUMPTION

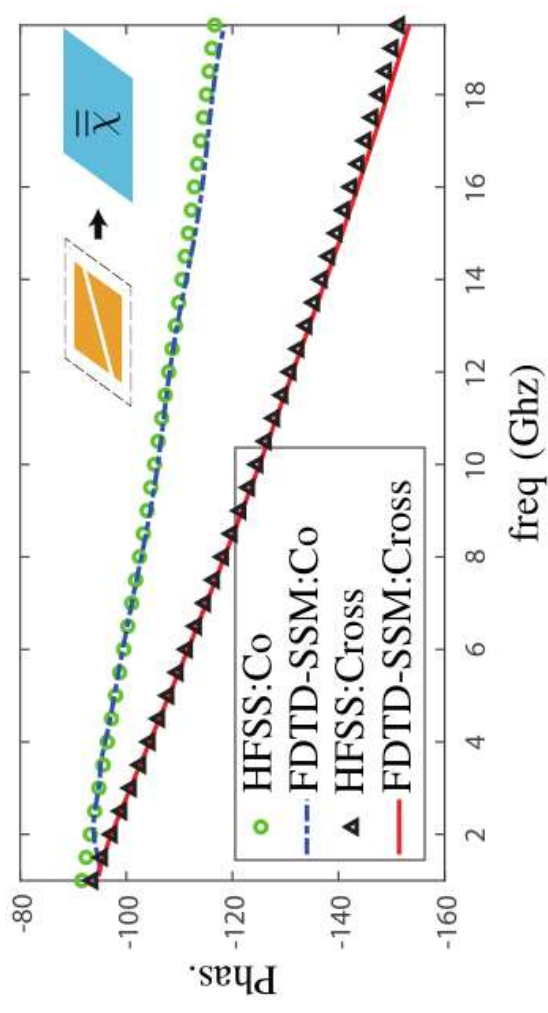
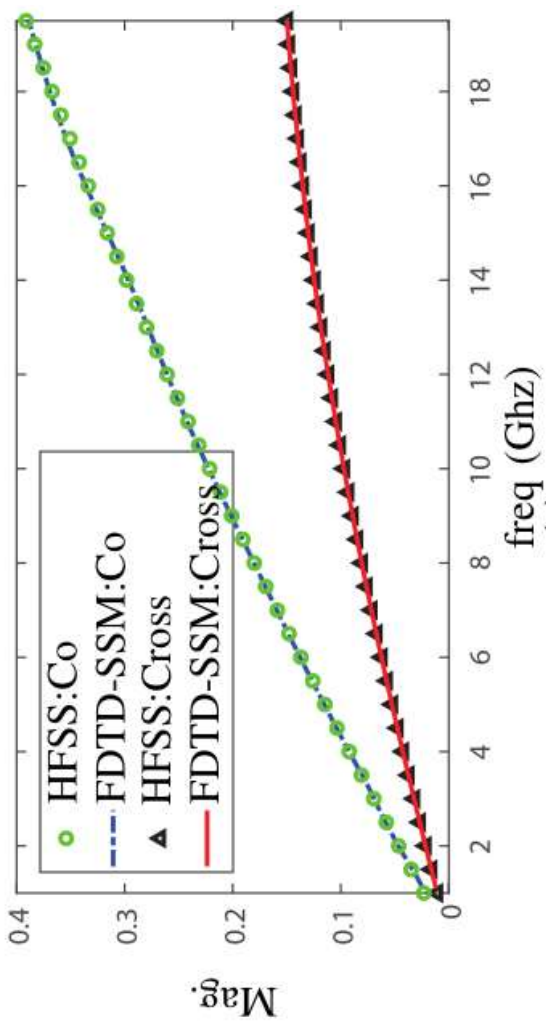
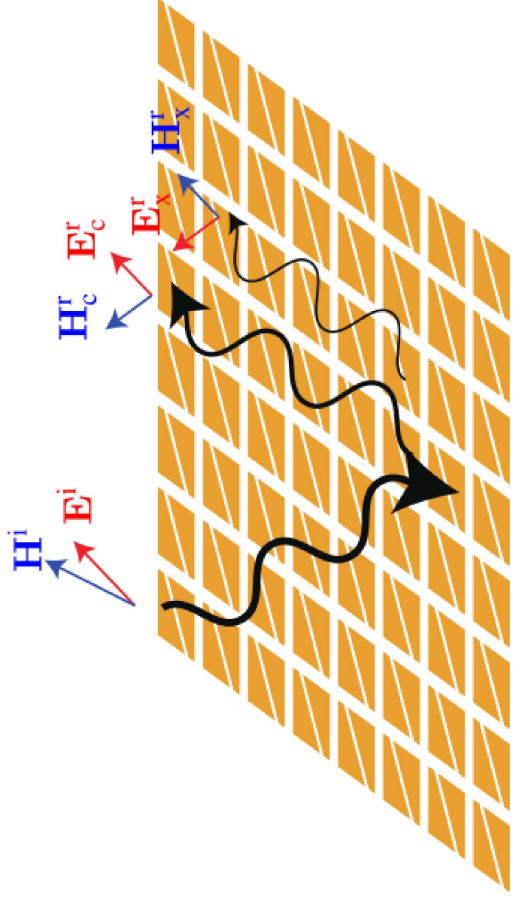
	cell size	time consum.
<b>Conv. FDTD</b>	$dx = dy = dz = 0.05 \text{ mm}$	1410 s
<b>FDTD-SSM</b>	$dx = dy = dz = 0.75 \text{ mm}$	3 s

**Remarks:**

1. The FDTD-SSM algorithm is valid for different polarizations of incident waves.
2. The computational time is greatly saved by adopting FDTD-SSM.



# Anisotropic FDTD-SSM



## Remarks:

1. For anisotropic cases, cross polarization exists.
2. Both co- and cross- polarization are validated by HFSS.



# Outline

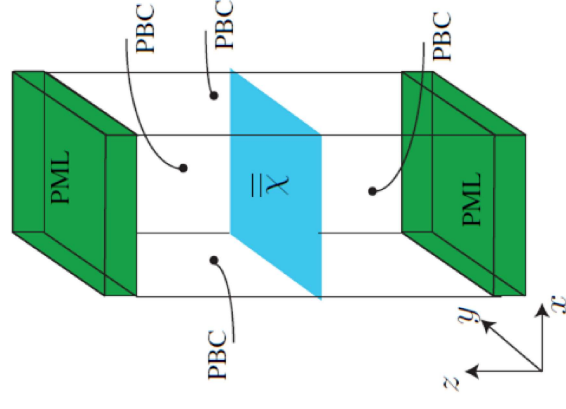
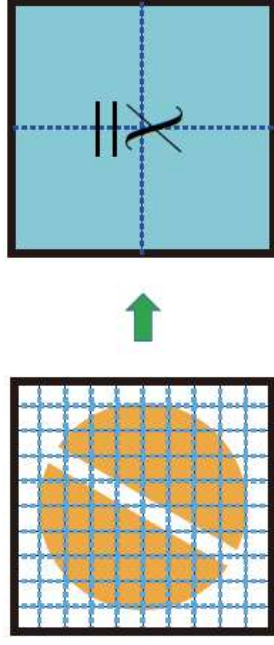
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- ◆ Introduction of Metasurfaces
- ◆ Modeling of metasurface
- ◆ FDTD-SSM Algorithm
- ◆ Numerical Experiments
- ◆ Conclusion

# Conclusion

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- A novel FDTD-SSM algorithm for accelerating metasurface simulation.
- Surface susceptibility model, Biaxial and anisotropic model, extraction
- surface currents in FDTD
- Advantages: **simple & efficient**
- Numerical experiments of the FDTD-SSM algorithm
- Reduction of meshing lattice size, effectiveness for different shapes
- Uniaxial, biaxial and anisotropic element shape
- Consuming time is reduced **from hours to seconds**.





# References

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**Thanks!**